



Autonomous Driving: Need for AI and New Architectures

March 25, 2019

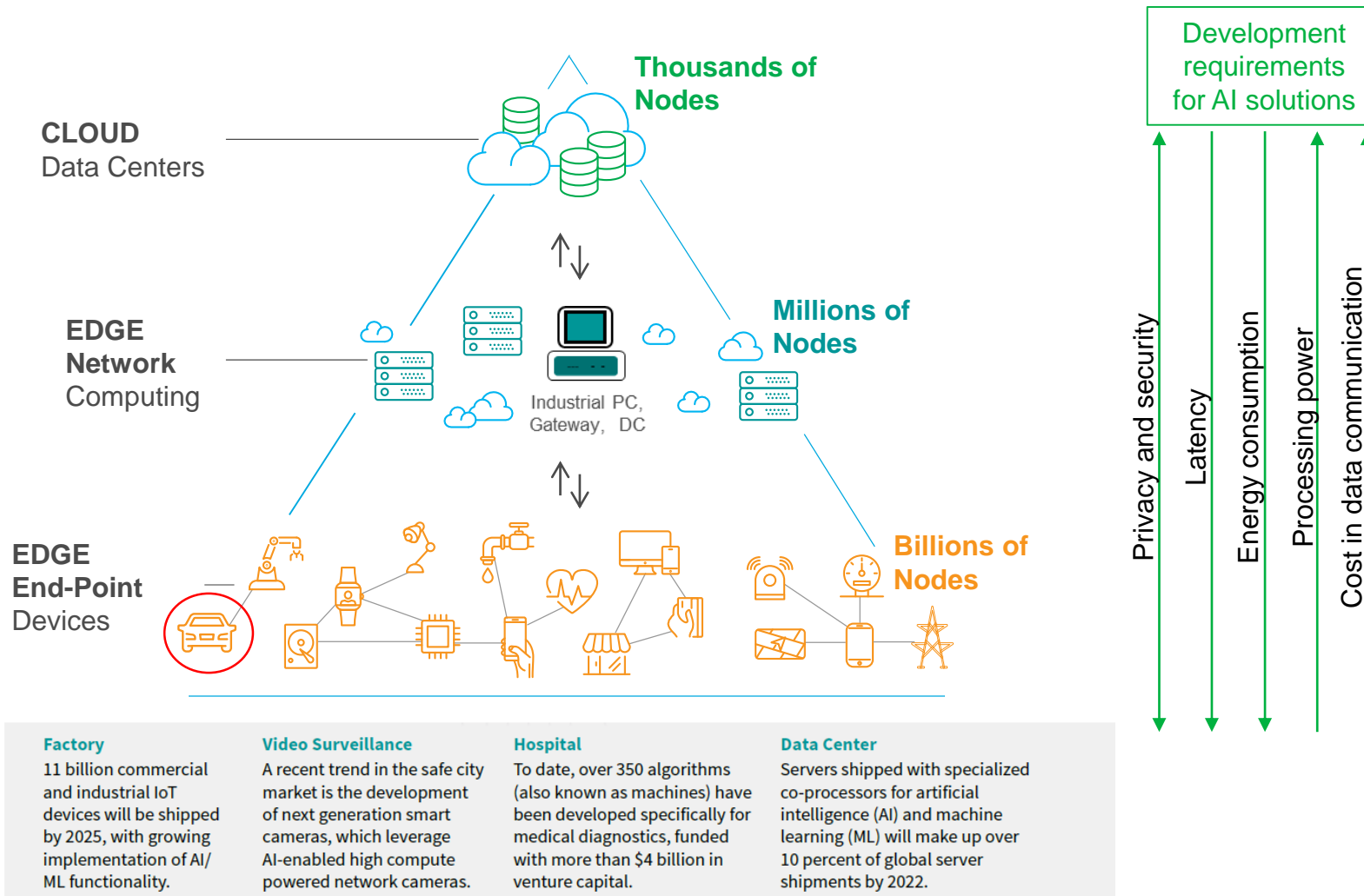
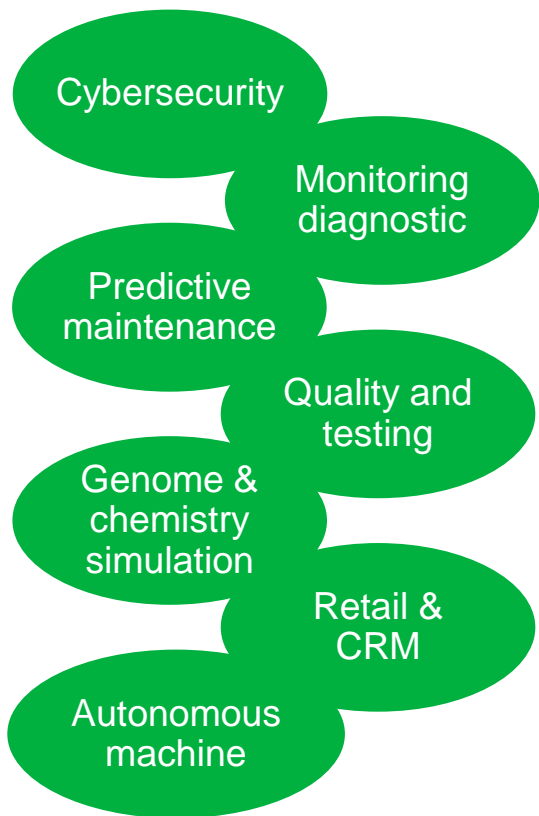
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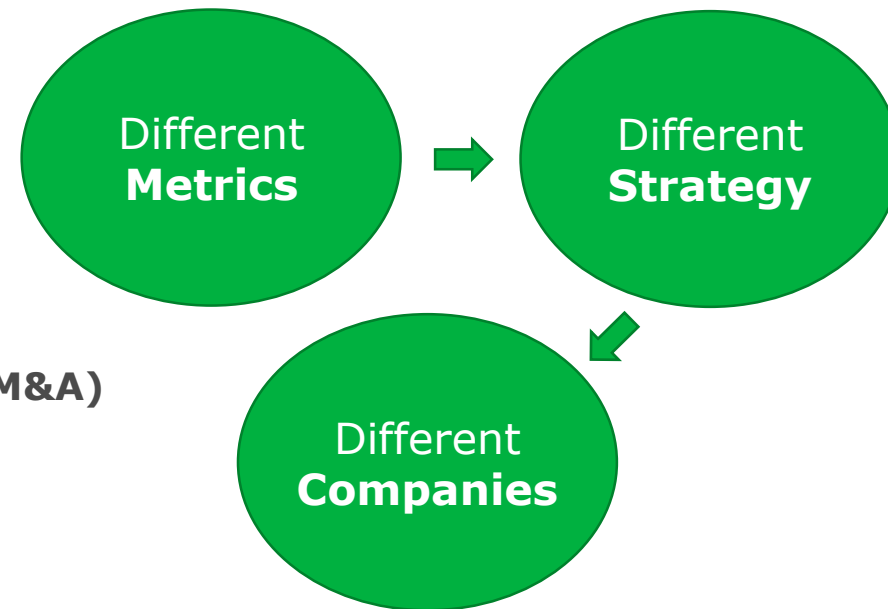
- AI pervasiveness
- Vehicle and Semiconductor market forecast
- Role of SoCs and AI-based systems in future cars
- Why AI in Automotive
- New E/E architectures required
- Growth of electronic content and costs by autonomy levels
- Software: a noble gas
- Open challenges and opportunities

AI is pervasive: everywhere at the Edge and at the Cloud

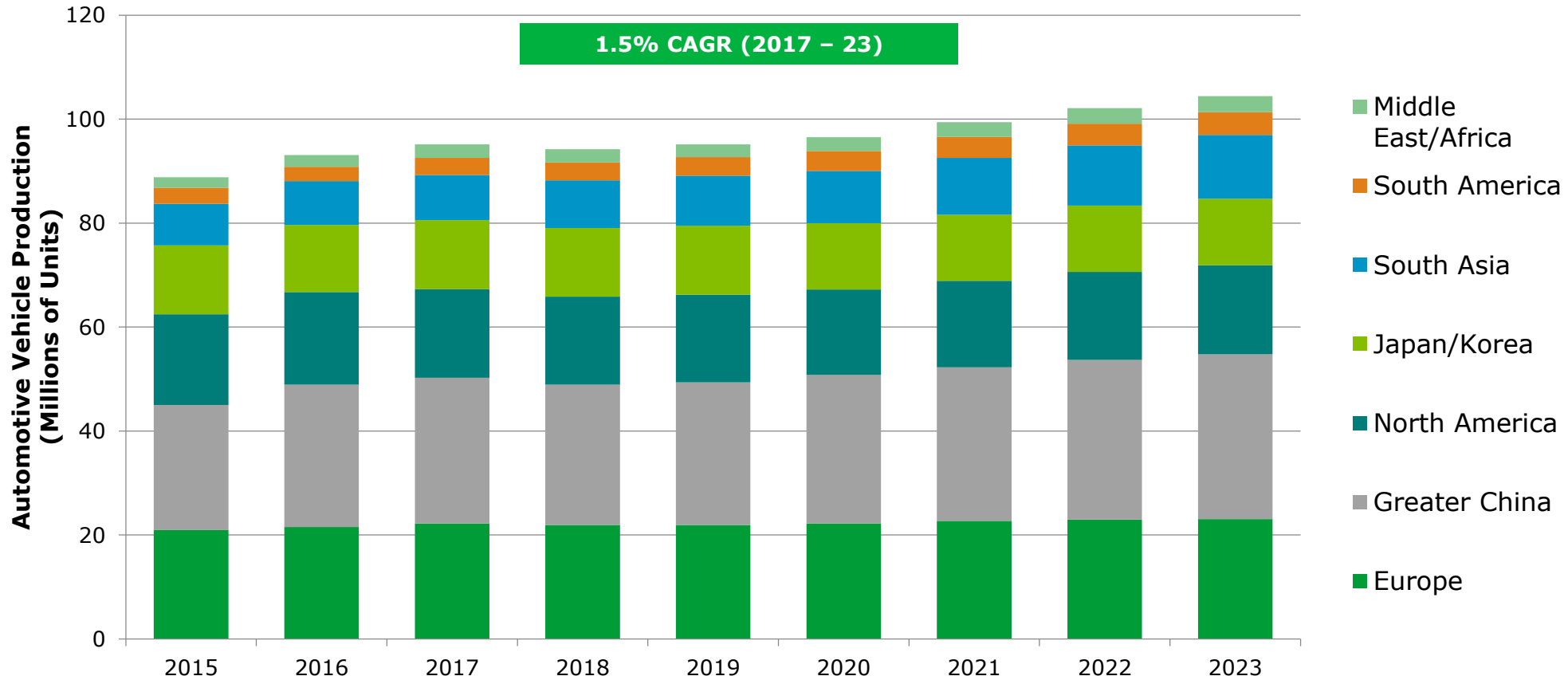


Different Metrics for Investment and Research engagement:

- > **Business Case:** Investment (Legacy Equipment, Process node and Product Life cycle) and ROI
 - Market Volumes (i.e. Shipment) vs Time frame
 - Revenue Expectation
 - Market Momentum & Growth expectation
 - Margin
 - Technology Readiness
 - Competition analysis
- > **Regulatory needs/assessment**
- > **Eco-system development and needs (Partner and M&A)**
 - Start-up and new players
- > **System Complexity (HW and SW)**
 - Memory and Interfaces
 - Key performance parameter:
 - Processing/Data workload, Latency, Power, Safety
 - Silicon differentiation in data-processing: GPU, CPU, TPU...up to Heterogeneous SoC;

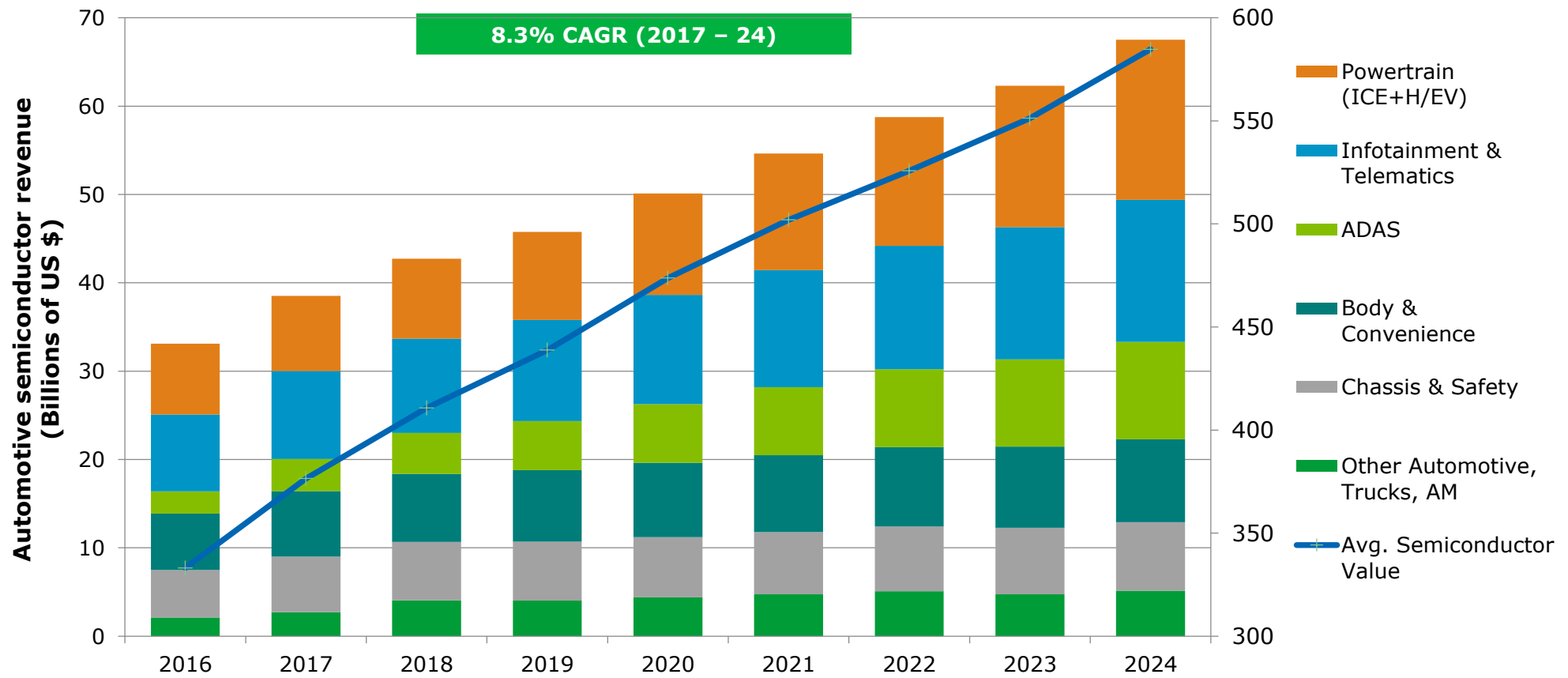


Vehicle production rises slowly



Electrification, automated driving and connectivity

Fueling automotive semiconductor growth



Implication of AI and Deep Learning

Major advantages in comparison with traditional machine vision

- **Assumptions:**

- > New silicon solutions will be developed with focus on AI algorithm
- > The functional safety aspect will be addressed by the entire supply chain

- **Deep learning can:**

- > Allow detection and recognition of multiple object → improve perception
- > Perform semantic analysis of the area surrounding the vehicle
- > Reduce development time of ADAS and IVI systems (once DL is in steady-state)
- > Reduce the power required compared to the same operation w/ traditional algorithms

- **Deep Learning needs help**

- > Recognition/Prediction of actions and Fusion - Bayesian Net and other stochastic algorithms may complement DL in the run to autonomous cars (L4-L5)

- **Required precondition:**

- > Telematics will be broadly deployed to: 1) enable gathering of “real” patterns and data for training 2) allow over the air system update and security

Extra Requirements for Deep Learning in **ADAS & AV**

- **DL in ADAS for Autonomous functions requires in-vehicle HW:**

- > Latency: for active function system needs to react in less than 70-80ms
- > Deep Learning offer deterministic latency also for “noisy” input from sensors
- > Performance: TFlop/TOP/TMAC is barely the minimum

- **Power:**

- > Individual sensor subsystems need to stay in the power budget of 4W;
- > Sensor Fusion ECUs might allow targets up to 15-20W or more. Some OEMs expect already they need to find a trade off if no silicon is available and performance needed.

- **Backhaul and data storage infrastructure:**

- > Connectivity (IoT) is a need to:
 - Store training data and vehicle parameters.
 - Update/Upgrade the system

• **Data acquisition** is a challenge for validation and test: mix **Real & Synthetic** data (Simulation)

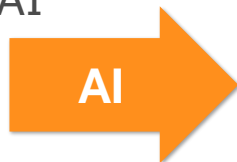
• **Safety** is the biggest uncertainty to have autonomous car based on AI.

Standardisation is a must have

Evolution of human machine interface (HMI)

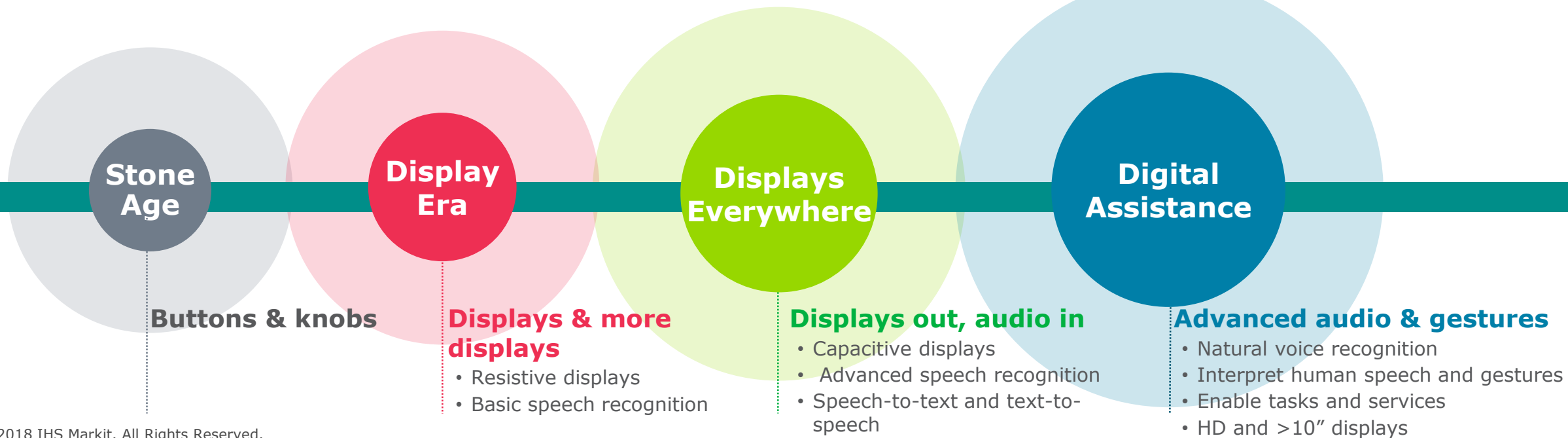
What pushed the changes?

- Diverse technologies: from displays to AI
- Lowered costs
- Influence of consumer electronics
- Increased customer needs



Why human machine interface?

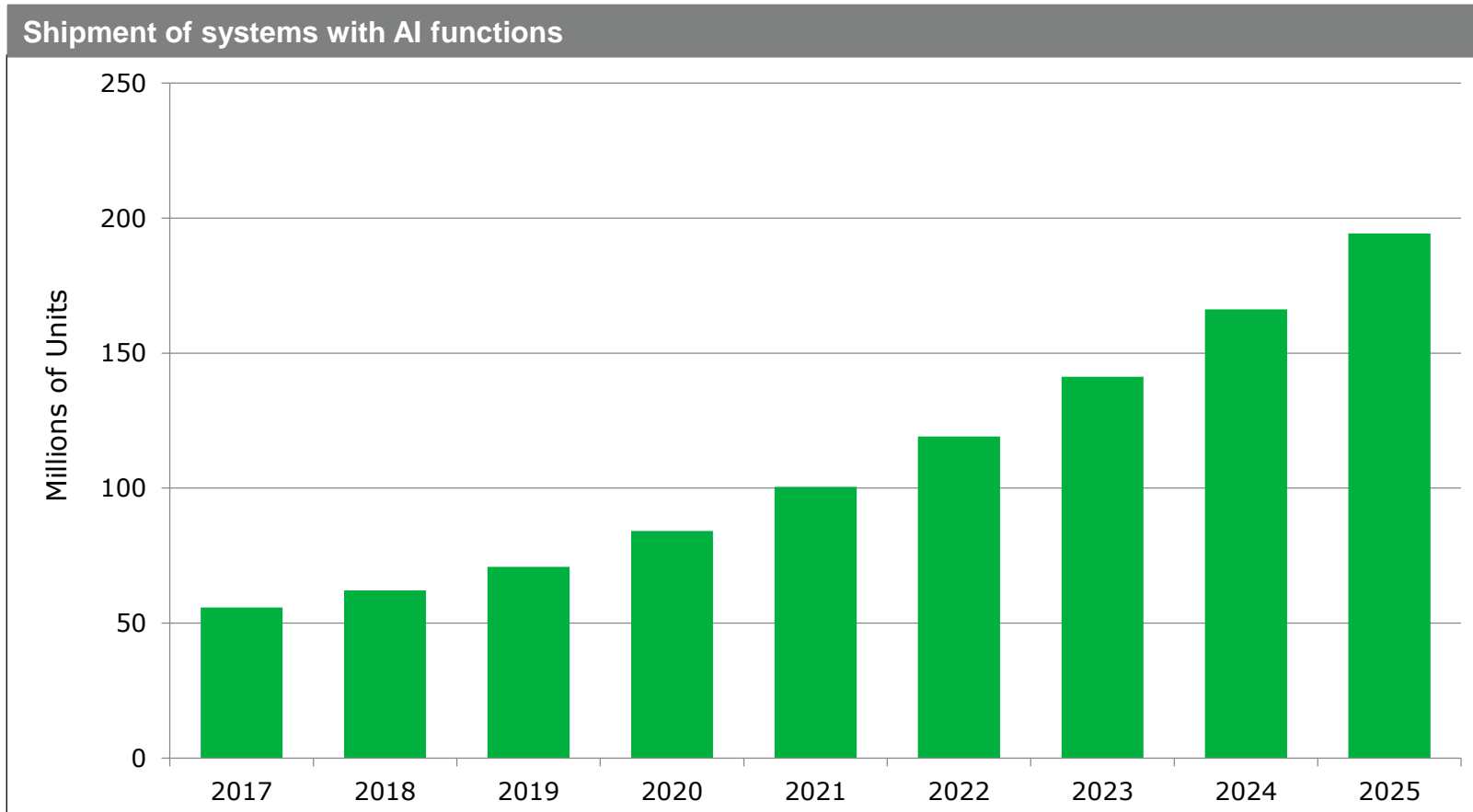
- High added value and brand differentiation
- Limited performance and cost
- Steady algorithms
- Available data
- Not safety critical
- **Ubiquitous across industries**



Cost, Performance and Power for Autonomous Vehicles: still far from high volumes vehicle production

- Power consumption is critical in automotive
 - ➔ where can compromises be acceptable?
- Performance $50 < \text{TOPS} < 100$ looks to be the target in L4-L5
 - ➔ is silicon today able to cope with it and ensure a long term roadmap?
- Sensor and ECU add up to several thousands of dollars
 - ➔ what is the Business Model?
 - ➔ where is the ROI?
- ISO26262 is the biggest challenge considering ML deployment

AI in Automotive: Infotainment and ADAS

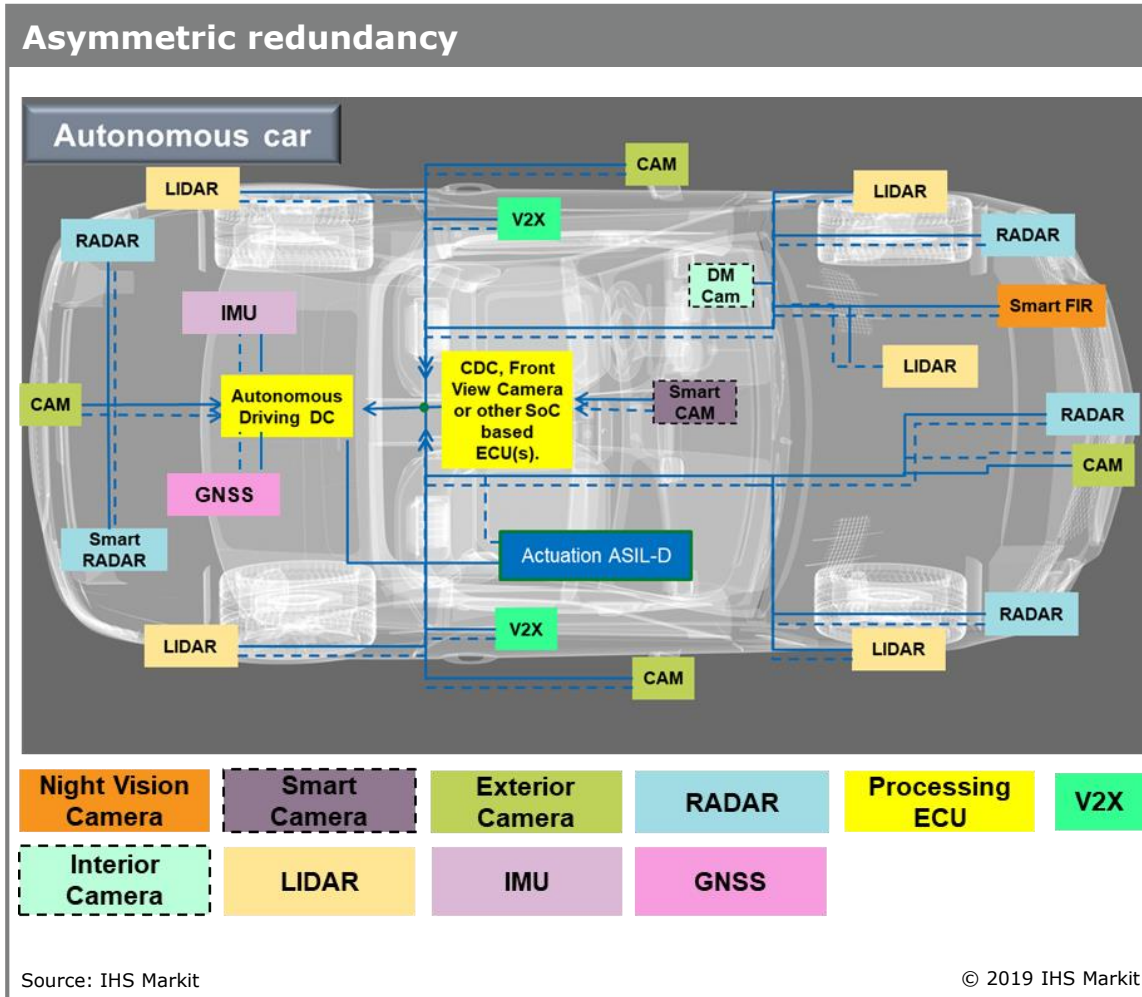


Typical ADAS content from level 3 to 5

ADAS Modules		L3	L4	L5
Radars	Ultrasonic Sensors	12	12	12
	Long-range Radar	1	1-2	1-2
	Short/Mid-range Radar	2-4	2-6	4-6
Cameras	Exterior Camera	5-8	12	8-15
	Interior Camera	1	1	1
	Night Vision Camera	0-1	0-1	0-1
Lidars	Long-range Lidar	~ \$2-3k	~ \$3-6k	~ \$6-9k
	Short-range Lidar	0-2	0-4	0-4
ECUs	ADAS Domain Controller	0-1	0	0
	Autonomous Driving DC	1	1-2	2
TOTAL (without ultrasonic)		14	22	25

*Architectures based on existing pilot car platforms from BMW, Volvo, Audi, Nissan..

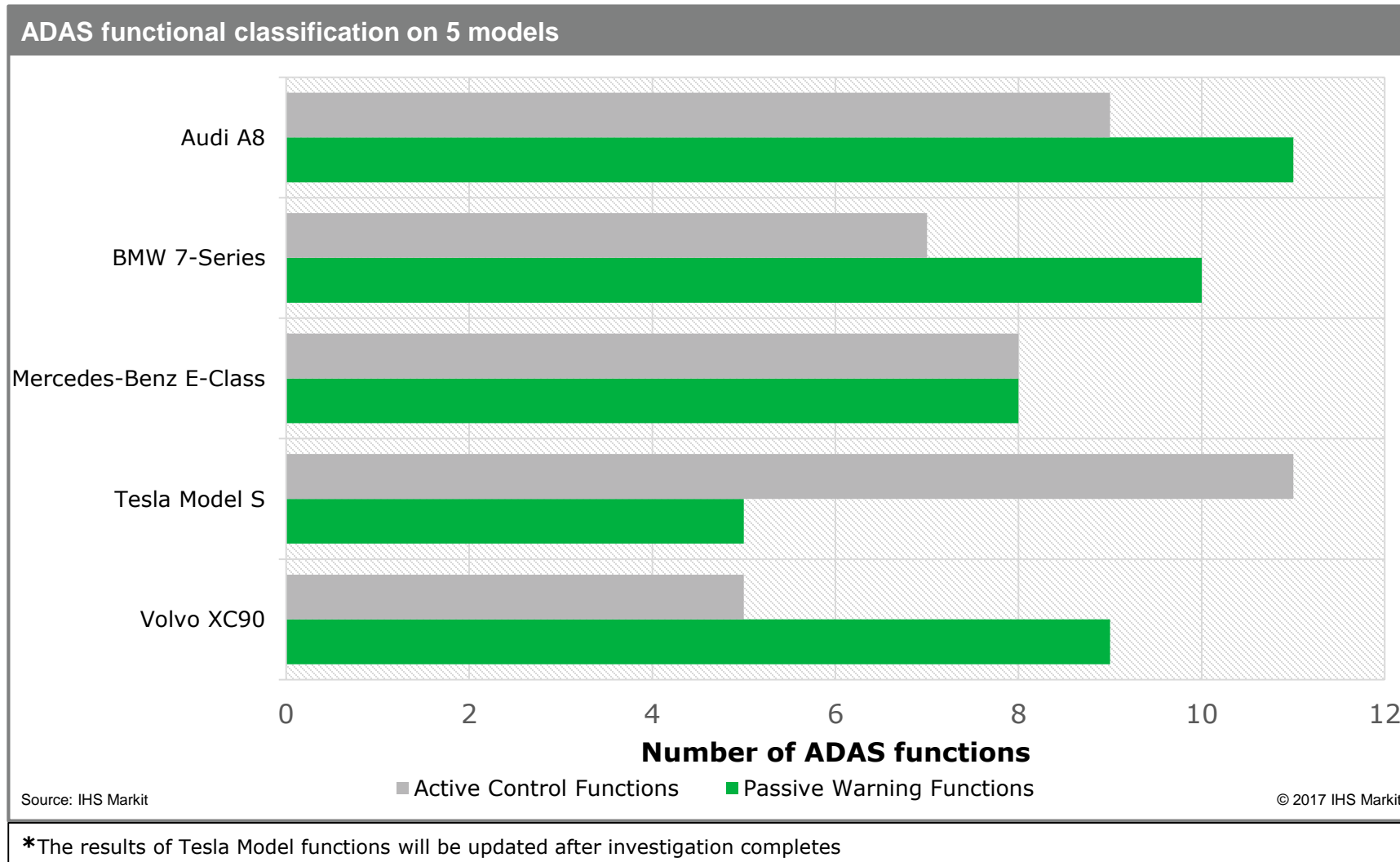
Possible architecture for L4/L5 in model year 202x



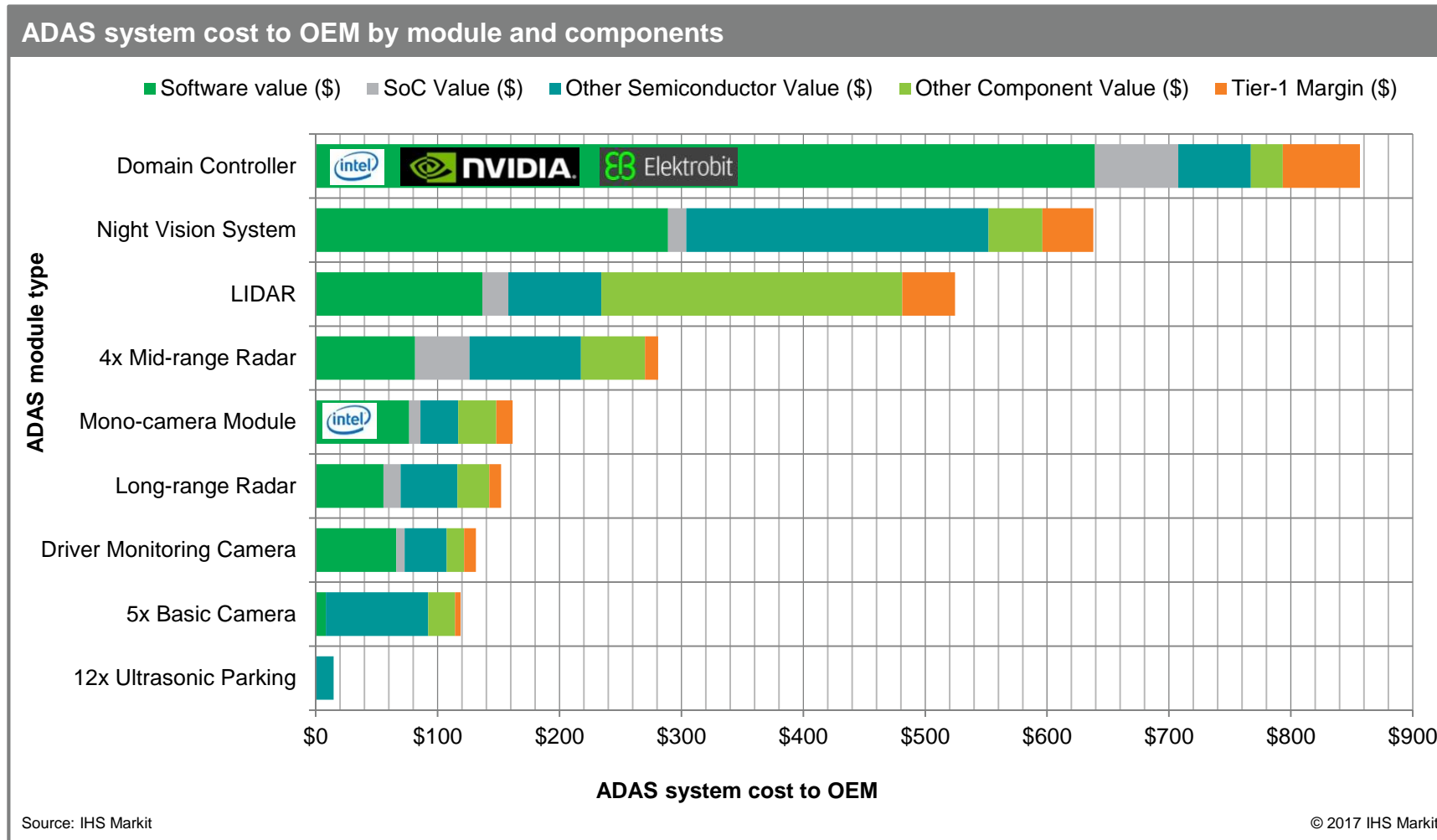
- No Driver - Redundancy for L4/L5 is key
 - > Two identical (or nearly) Domain Controllers
 - Provides complete redundancy.
 - Expensive but comprehensive.
 - DC2 can either share normal operations with DC1 or act just a back up.
 - Redundant network and power supply
 - > Limited or distributed redundancy
 - Cockpit Domain Controller (CDC) and/or Front View Camera are candidates because of their processing capabilities.
 - Lower cost than symmetric redundancy but maybe less comprehensive.

*DC= Domain Controller

ADAS classification by passive warning and active control



ADAS system cost to OEM by component value on Audi A8



*Price of SOC does not include software value.

Thanks for your attention

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